

# **Use of 2D-Video Disdrometer to Derive Mean Density-Size and $Z_e$ -SR Relations: Four Snow Cases from the Light Precipitation Validation Experiment**

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## ABSTRACT

The application of the 2D-video disdrometer to measure fall speed and snow size distribution and to derive liquid equivalent snow rate, mean density-size and reflectivity-snow rate power law is described. Inversion of the methodology proposed by Böhm provides the pathway to use measured fall speed, area ratio and '3D' size measurement to estimate the mass of each particle. Four snow cases from the Light Precipitation Validation Experiment are analyzed with supporting data from other instruments such as Precipitation Occurrence Sensor System (POSS), Snow Video Imager (SVI), a network of seven snow gauges and three scanning C-band radars. The radar-based snow accumulations using the 2DVD-derived  $Z_e$ - $SR$  relation are in good agreement with a network of seven snow gauges and outperform the accumulations derived from a climatological  $Z_e$ - $SR$  relation used by the Finnish Meteorological Institute (FMI). The normalized bias between radar-derived and gauge accumulation is reduced from 96% when using the fixed FMI relation to 28% when using the  $Z_e$ - $SR$  relations based on 2DVD data. The normalized standard error is also reduced significantly from 66% to 31%. For two of the days with widely different coefficients of the  $Z_e$ - $SR$  power law, the reflectivity structure showed significant differences in spatial variability. Liquid water path estimates from radiometric data also showed significant differences between the two cases. Examination of SVI particle images at the measurement site corroborated these differences in terms of unrimed versus rimed snow particles. The findings reported herein support the application of Böhm's methodology for deriving the mean density-size and  $Z_e$ - $SR$  power laws using data from 2D-video disdrometer.

## 1. Introduction

The measurement of liquid equivalent snow rate ( $SR$ ) from radar has long been recognized as a difficult problem in quantitative precipitation estimation (QPE) but one of great importance for weather forecasting, hydrology, detection of aviation hazards and other remote sensing applications (e.g., ground validation for microwave radiometry from space). The validation of QPE by radar is difficult at best given the fact that accurate measurement of winter precipitation by gauges remains challenging due to the sheer variety and variability of physical properties which can change dramatically with, for example, relatively small changes in environmental conditions. Some of the important physical properties that one could list, for example, are (i) '3D'-size, (ii) terminal fall speed, (iii) particle size distribution, (iv) density (or, mass), (v) shape, (vi) composition and (vi) porosity. Some of these attributes are not independent as evidenced by the large literature that exists in describing density (or, mass)-size and fall speed-size relations for different kinds of winter precipitation (e.g., Pruppacher and Klett 2010; Mason 2010). The fall speed is also dependent on shape, composition and porosity. Thus, it follows that fall speed is fundamental to characterization of frozen precipitation followed by a good measure of '3D'-size, particle size distribution and porosity. From the radar reflectivity perspective, the '3D'-size and associated size distribution and the density (or, mass)-size relation is of fundamental importance. For Rayleigh scattering the reflectivity is directly related to  $E[m(D)^2]$  where  $m$  is the particle mass and  $E$  stand for expectation or integration over the size distribution (Ryzhkov et al. 1998); however, the mass is not easily measured on a particle-by-particle basis. On the other hand, the liquid equivalent snow rate ( $SR$ ) is directly related to  $E[m(D) V_f(D)]$

where  $V_f$  is the fall speed. It follows that empirical  $Z_e$ - $SR$  power laws can be derived if mass- $D$  and  $V_f$ - $D$  power laws are assumed (e.g., Matrosov et al. 2009) and the size distribution is measured (e.g., Sekhon and Srivastava 1970). The simulations of Matrosov et al. (2009) suggest that the overall uncertainty of estimating  $SR$  from reflectivity measurements can be as high as a factor of 3 or so. A more direct method is to correlate  $Z_e$  from radar with  $SR$  measured by snow gauges (e.g., Fujiyoshi et al. 1990 and references therein) which can lead to climatological  $Z_e$ - $SR$  power law. The advent of optical-based surface disdrometers, however, has led to more accurate methods to characterize the physical properties of snow, leading to  $m$ - $D$ ,  $V_f$ - $D$  and area ratio- $D$  relations that are consistent via hydrodynamic theory (Böhm 1989; Mitchell 1996; Heymsfield and Westbrook 2010). Combined with scattering models (size, shape, dielectric constant), it leads to more consistent  $Z_e$ - $SR$  power laws (Huang et al. 2011).

There are a number of disdrometers (mainly optical) that are available (some commercial and others in the research category) that measure a sub-set of the physical parameters listed above (only instruments that can image the particles are considered here). Hanesch (1999) and Schönhuber et al. (2000) used the 1<sup>st</sup> generation 2D-video disdrometer (2DVD) which measures fall speed and two orthogonal images from which an apparent volume (also, size distribution based on '3D'-size) as well as an estimate of porosity (via the area ratio to be described later) can be computed. Later, Brandes et al. (2007) used the 2DVD to estimate the coefficient and exponent of a mean density- $D_0$  power law (mainly for fluffy snow aggregates) by comparing 15-min liquid water accumulations with a collocated Geonor gauge ( $D_0$  is the median volume diameter of

68 the particle size distribution). They also examined the particle size distribution in detail  
69 by fitting with a gamma model and deriving correlations between the model parameters  
70 (e.g., shape parameter  $\mu$  and slope parameter  $\Lambda$ ). They conclude (in their Section 6,  
71 page 648) that, "...The video disdrometer is a powerful observational tool for studying  
72 the microphysical properties of winter storms". Further, Brandes et al. (2008)  
73 investigated power law relation between terminal fall speed and size and its  
74 dependence on temperature. The use of radar and 2DVD for estimating density-size  
75 and  $Z_e$ -SR power laws is described by Huang et al. (2010; 2011) whereas Zhang et al.  
76 (2011) demonstrated the importance of density-size power laws (empirically adjusted by  
77 fall speed) in comparing 2DVD-based reflectivity with ground radar. While the 2DVD is  
78 commercially available, a similar research instrument HVSD (Hydrometeor Velocity Size  
79 Detector; Barthazy et al. 2004) measures the fall speed and projected image in one  
80 plane. It has been used by Zawadzki et al. (2010) to investigate the natural variability of  
81 snow terminal velocity with size. They concluded that the exponent of the terminal  
82 velocity- $D$  power law could be fixed at 0.18, while the coefficient is variable from event-  
83 to-event. Szyrmer and Zawadzki (2010) describe a methodology to derive the average  
84 relationship between terminal fall velocity and the mass of snowflakes via elaboration of  
85 the methodology of Böhm (1989) proposed by earlier Hanesch (1999); the latter used  
86 the 1<sup>st</sup> generation tall 2DVD design. In fact, the development of the HVSD by Barthazy  
87 et al. (2004) followed Hanesch and lead to a simpler instrument with two parallel light  
88 planes but with much slower line scan frequency camera. The work described herein  
89 follows Szyrmer and Zawadzki (2010) but uses the 2<sup>nd</sup> generation low profile 2DVD

(Schöenhuber et al. 2008) to derive the  $Z_e$ -SR power law with validation provided by a network of seven snow gauges.

Another research instrument is the Snow Video Imager (SVI; Newman et al. 2009) which, unlike the line scan camera, uses a CCD (charge-coupled device) full frame camera (60 frames per second) and images are obtained almost simultaneously; however, it does not measure the fall speed. SVI software yields a size estimate of each particle as an equivalent diameter that corresponds to a circular equivalent-area diameter of the irregular shape (with holes filled). Some advantages of the SVI over the 2DVD is that it has a large sample volume (twice that of the 2DVD), better pixel resolution (nominally 0.05 mm by 0.1 mm) and its measurements are less sensitive to wind. In this work, the SVI is mainly used to determine the particle size distribution for comparison with the 2DVD, and to examine samples of images to distinguish between unrimed and rimed snow particles. A new commercially available instrument is the Multi-Angle Snowflake Camera (MASC; Garrett et al. 2012) which gives high resolution (10-50  $\mu$ m) photographs of snow particles from three viewing angles, along with their fall speed. One disadvantage is that the sample volume is small (about 1/10 of the 2DVD).

This article is organized as follows. In Section 2 the specific details of estimating the apparent volume and '3D'-apparent diameter, the adjusted particle size distribution and the application of Böhm's (1989) method are described. Section 3 constitutes the main bulk of the article and describes the 2DVD processing and derived products culminating

in  $Z_e$ -SR power laws for the four snow days, comparison of liquid equivalent snow accumulations derived from radar with a network of 7 snow gauges, and radar-based accumulation maps. A short summary and conclusions are given in Section 4.

## 2. The basis for snow measurements using the 2D-video disdrometer

### 2.1 The apparent volume and diameter

The 2DVD gives two views (front and side views; actually silhouettes) of the particle in two orthogonal planes as shown in the example in Fig. 1. It is obvious that the ‘true’ volume of such an irregular particle cannot be calculated and thus we define here the apparent volume ( $VL_{app}$ ) assuming that the particle is an ellipsoid. The apparent volume is defined as an average of two ellipsoidal volumes:

$$VL_{app} = \frac{\pi}{6} D_{app}^3 = \frac{VL_{app1} + VL_{app2}}{2} \dots\dots\dots(1)$$

where the apparent diameter is  $D_{app}$  and,

$$VL_{app1} = \frac{\pi}{6} (H * W_1 * W_2) \dots\dots\dots(2)$$

where,

$$H = \sqrt{H_1 * H_2} \dots\dots\dots(3a)$$

$$W_{1,2} = \frac{4 * A_{e1,2}}{\pi * H} \dots\dots\dots(3b)$$

The  $A_{e1,2}$  are the shadow areas (see Fig. 1) from the two views. The second ellipsoid estimate,  $VL_{app2}$ , is defined as:

$$VL_{app2} = \frac{\pi}{6} (HH * W_{max1} * W_{max2}) \dots\dots\dots(4)$$

where,

$$HH = \sqrt{HH_1 * HH_2} \dots\dots\dots(5a)$$

$$HH_{1,2} = \frac{4 * A_{e1,2}}{\pi * W_{max1,2}} \dots\dots\dots(5b)$$

In (5b) the  $W_{max}$  equals the maximum width of the scan line or ‘slice’ (measured from left to right in Fig. 1); the subscripts 1,2 refer to maximum width as determined from each view. The method of calculating  $VL_{app}$  and  $D_{app}$  here generally follows Hanesch (1999) which is somewhat different from Schönhuber et al. (2000) which was used later by Brandes et al. (2007). Also, the apparent diameter ( $D_{app}$ ) is different from the ‘size’ measured by instruments that give the particle image in only one plane such as aircraft-mounted imaging probes (which give the top view). The ‘size’ is often defined as the maximum distance between two pixels or the diameter of the smallest circle that completely circumscribes the image or the equivalent-area diameter (Hogan et al. 2012). The latter also define the mean diameter as the mean of the particle dimensions in two orthogonal directions which they found to be better related to radar reflectivity. Since the true volume of snowflake is not known, the accuracy of our method of calculating  $VL_{app}$  cannot be determined. However, from the simulations of Wood et al. (2012) who used ellipsoidal shape models with canting it is can be inferred that the apparent diameter defined here gives a more ‘realistic’ measure of ‘3D’ size made possible by the availability of two orthogonal images from the 2DVD.

## 2.2 Snow size distribution (SSD)



In a certain time window (typically 60 seconds for 1-minute averaged size distributions), all ‘matched’ snow particles are sorted into  $M$  size bins according to the apparent diameter ( $D_{app}$ ) and the ‘un-adjusted’ size distribution  $N_m(D_i)$  is computed as:

$$N_m(D_i) = \frac{1}{\Delta t * \Delta D} \sum_{j=1}^{N_i} \frac{1}{A_j * v_j} \quad [mm^{-1} m^{-3}] \dots\dots\dots(6)$$

where  $D_i$  is the center diameter of the  $i^{th}$  size bin (from 1 to  $M$ ) in mm;  $\Delta D$  is the bin width in mm;  $A_j$  is the measurement area in  $mm^2$ ;  $v_j$  is the fall speed in  $m s^{-1}$  and  $\Delta t$  is the time window in seconds. The fall speed measurement is fundamental to the 2DVD and relies on the ability to match the particle that falls in the upper light plane (and is imaged by Camera A) to the same particle that falls through the lower light plane and is imaged by Camera B (see Fig. 2). The match criteria used here are adapted from Hanesch (1999) as elaborated by Huang et al. (2010). If the match criteria are not satisfied then that particle is rejected; it follows that the concentration will tend to be under-estimated. To re-adjust the measured  $N_m(D_i)$  for this underestimate (assumed to be a constant factor  $\gamma$ ) the following procedure is used.

Assume that snow falls uniformly over the instrument. Then, the theoretical number of snowflakes falling through the virtual measuring area divided by the theoretical number of snowflakes falling in the scan area of each camera (shown in Fig. 2) should be equal to the ratio of these two areas as:

$$\frac{\text{theoretical \# of snowflakes in virtual measuring area}}{\text{theoretical \# of snowflakes in scan area of single camera}} = \frac{100}{250} = 0.4 \dots\dots\dots(7)$$

Therefore, an adjustment factor  $\gamma$  is derived as:

$$\gamma = \frac{0.4 * (\# \text{ of snowflakes actually counted in scan area of single camera})}{\# \text{ of matched snowflakes in virtual measuring area}} \dots\dots\dots(8)$$

The “re-adjusted” concentration in each size channel ( $N(D_i)$ ) is defined as:

$$N(D_i) = \gamma * N_m(D_i) \dots\dots\dots(9)$$

where  $\gamma$  is assumed constant ( $\gamma \geq 1$ ). In essence, the “raw” or unadjusted SSD is simply scaled by the factor  $\gamma$ . The validity of this adjustment will be evaluated by comparison with SSD from the snow video imager (Newman et al. 2009) as well as determining the  $\gamma$  independently by comparison with the SVI as described later in Section 3.1.

### 2.3 Böhm’s Method

Böhm (1989) developed a general methodology for the terminal fall speed of solid hydrometeors based on the mass, the mean effective projected area ( $A_e$ ; see Fig. 3, also referred to as shadow area) presented to the flow, and the smallest circumscribed area ( $A$ ; circle or ellipse depending on the shape of the snow particle). Since the 2DVD can measure the fall speed of each snowflake as well as two orthogonal images (Fig. 1), we are able to compute the mass of each snowflake by inverting the Böhm equations. The assumption is that  $A_e$  which is the projected area in a plane normal to the flow, is approximately equal to the area from the side or front views (measured by the 2DVD) for irregular shaped particles. This assumption has been evaluated as being ‘reasonable’ by Szyrmer and Zawadzki (2010) who use the HVSD which gives the side view only. We first compute the Reynolds number ( $Re$ ) from fall speed ( $V_f$ ) and viscosity ( $\eta$ ) as:

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$$Re = \frac{2 * \rho_a * V_f}{\eta} \left( \frac{A}{\pi} \right)^{\frac{1}{2}} \dots\dots\dots (10a)$$

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where the characteristic dimension is the ‘area’ diameter ( $A$  being the area of the smallest circumscribed ellipse or circle that completely encloses the particle image).

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The  $\eta$  and air density ( $\rho_a$ ) are computed from temperature, air pressure and humidity.

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Next, we compute the Davies number ( $X$ ) from  $Re$  as:

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$$X = \left\{ \frac{\left[ \left( \frac{Re}{8.5} \right)^{\frac{1}{2}} + 1 \right]^2 - 1}{0.1519} \right\}^2 \dots\dots\dots (10b)$$

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Finally the mass of the snowflake is computed as:

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$$m = \frac{\pi * \eta^2 * X}{8 * g * \rho_a} \left( \frac{A_e}{A} \right)^{1/4} \dots\dots\dots (10c)$$

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where  $g$  is the acceleration due to gravity. The ratio ( $A_e/A$ ) is referred to as the ‘area ratio’ or  $A_r$  which is  $\leq 1$ . The MKS units are appropriate for the variables in (10). The

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relative error in the estimate of mass due to uncertainty in the fixed relation between  $X$

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and  $Re$ , and in the estimation of  $A_r$  has been evaluated by Szyrmer and Zawadzki

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(2010) as between 40-50%. The propagation of error from (10a) to (10c) is complicated

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and the reader is referred to the aforementioned reference for details.

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The calculation of the minimum circumscribed area ( $A$ ) is based on the rectangle which

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completely encloses the particle (the rectangle width is  $W_r$  and height is  $H$ ; see Fig. 1).

We first assume that, (i)  $A$  is the maximum ellipse that can be fitted inside the rectangle and compute the area ratio  $A_e/A$  which should be  $\leq 1$ . If this ratio is greater than 1, we assume that, (ii)  $A$  is the minimum circle that can contain the rectangle. The minimum circumscribed area estimated from (i) usually tends to underestimate  $A$  whereas from (ii) tends to overestimate  $A$ . The apparent volume ( $VL_{app}$ ) and apparent diameter ( $D_{app}$ ) were defined earlier, thus the density ( $\rho$ ) is obtained as the ratio of mass ( $m$ ) to  $VL_{app}$  for each particle. Since our measurements are restricted to frozen ice precipitation, the density is also restricted to  $\min[m/VL_{app} \ 0.917]$  in cgs units. The mean density is calculated for each size bin and a power law fit of the form  $\rho = \alpha D_{app}^\beta$  is obtained for the precipitation event. Here  $D_{app}$  is in  $mm$  and  $\rho$  is in  $g \text{ cm}^{-3}$ . The mass- $D_{app}$  power law then is  $m = \alpha(\pi/6)D_{app}^{\beta+3}$ .

For an area sampling measurement device such as the 2DVD, the liquid equivalent snow rate ( $SR_m$ ) can be computed directly as:

$$SR_m = \frac{3600}{\Delta t} \sum_{i=1}^N \sum_{j=1}^M \frac{VL_j}{A_j}; \quad [mm \text{ hr}^{-1}] \dots \dots \dots (11),$$

where  $N$  is the number of size bins,  $M$  is the number of snowflakes in the  $i^{\text{th}}$  size bin in  $\Delta t$  (typically 60 seconds),  $VL_j$  is the liquid equivalent volume of  $j^{\text{th}}$  snowflake in  $mm^3$  (this is the product  $\rho VL_{app}$  where  $\rho$  as a function of  $D_{app}$  is given by the power law fit) and  $A_j$  is the measurement area for the  $j^{\text{th}}$  snowflake in unit of  $mm^2$ . The adjusted snow rate is  $SR = \gamma * SR_m$  where the  $\gamma$ -factor was defined in Section 2.2.

We use the T-matrix (Waterman 1971; Barber and Yeh 1975) method to compute the radar cross-section of each particle and the equivalent reflectivity assuming:

- Refractive index: computed by the Maxwell-Garnet (1904) mixing formula with temperature from environmental data. The particle is assumed to be a mixture of ice inclusions within an air matrix with effective density  $\rho$  as a function of  $D_{app}$  as given by the 2DVD-derived power law fit
- Orientation: the zenith angle is Gaussian with zero mean and  $45^\circ$  standard deviation; the azimuthal angle is uniformly distributed in  $[0 \pi]$
- Particle Size Distribution: as in Section 2.2 which defines  $N(D)=\gamma*N_m(D)$
- Particle shape: oblate spheroid with volume =  $VL_{app}$  and axis ratio = 0.8

### 3. Experimental Data from LPVEx

The Light Precipitation Validation Experiment (LPVEx) was held in the Fall of 2010 in the area surrounding Helsinki, Finland as a collaborative project between the Finnish Meteorological Institute (FMI), University of Helsinki and the NASA Ground Validation program (Petersen et al. 2011). While the experiment had multiple objectives and extensive suite of instruments, the focus herein is on snow measurements made at the Järvenpää site with the 2D-video disdrometer; this site also had the Precipitation Occurrence Sensor System (POSS; Sheppard and Joe 2008), the Snow Video Imager (SVI; Newman et al. 2009) and an OTT-PLUVIO2 gauge with Tretyakov and Alter shields (Ianza et al. 2006; Rasmussen et al. 2012). Three C-band polarimetric radars located at Kumpula, Vantaa and Kerava (Koskinen et al., 2011) provided for excellent

coverage over the Järvenpää site as well as over the network of six FMI snow gauges. Fig. 4 shows the location of the 3 radars, the Järvenpää site and the gauge network. Briefly, the three radars are nearly identical with  $1^\circ$  beams and using simultaneous H-V polarization on transmit and simultaneous reception of the H and V polarized back-scattered signal components via two receivers. The minimum detectable  $Z_e$  is about -10 dBZ at range of 50 km. The reflectivity data from each radar covering matched areas of precipitation were used to construct the CDF of  $Z_e$  enabling accurate cross-calibration of the radars (Hirsikko et al, 2013). All the radars are Vaisala dual-polarization weather radars, a detailed description of Vantaa radar operations is presented by Saltikoff and Nevvonen, (2011).

Table 1 lists the four snow days where there was significant precipitation in Helsinki and surrounding areas. The snow events on these days were also favorable for 2DVD and other snow measuring instruments as the wind speeds were  $< 4 \text{ m s}^{-1}$  at the Järvenpää site. As seen in Table 1, the 30 Dec 2010 case could be sub-divided into two snow events based on the synoptic conditions. Similarly, the first event on 12 Jan 2011 (0800-1230 UTC) could be separated from the second event that covered the period 2230-2359 UTC which further continued the next day (13 Jan) until 0500. The liquid equivalent snow accumulations (SA) from the OTT-PLUVIO gauge ranged from 1.5 to 4.2 mm.

### *3.1 Example of 2DVD processed data from 30 Dec 2010*

As mentioned earlier, one of the fundamental measurements provided by the 2DVD is the fall speed, an example of which is provided in Fig. 5 from the first event on 30 Dec 2010. The instrumental error in measuring terminal fall speeds is  $< 4\%$  (for fall speeds  $< 10 \text{ m s}^{-1}$ ; Schönhuber et al. 2008). Such high accuracy is due in part to the plane distance calibration which is performed frequently and accounts for slight deviations in the plane distance depending on the location within the virtual measurement area (see Fig. 2); further the line scan frequency is quite high close to 55 kHz. Zawadzki et al. (2010) evaluated the fall speed measurement error for the HVSD which, to the best of our knowledge, does not account for plane distance deviations within the measurement area plus the line scan frequency is much lower, closer to 10 kHz. They estimated that the instrumental uncertainty for the HVSD is around 12% for fall speeds below  $2 \text{ m s}^{-1}$ . While a similar analysis has not been done for the 2DVD, the contribution of instrumental error to the fall speed is expected to be much smaller than the natural variability which is depicted by the  $\pm 1\sigma$  bars in Fig. 5. It is also evident that the commonly used power law fit for  $V_f$  versus  $D$ , while analytically convenient, does not fit the data as well as an exponential fit of the form  $V_f = c[1 - d \cdot \exp(-\kappa D_{app})]$ .

The snow size distribution (SSD) for the same event is shown in Fig. 6a where the distribution from 2DVD is compared with that derived from the Snow Video Imager (SVI). The  $\gamma$ -factor was estimated as 2.21 (Section 2b and eq. 8). Fig. 6b shows similar plot for 6 Jan. 2011 event. The agreement in the SSD is quite good given that the two instruments are based on distinctly different measurement principles and sample volumes.

As a further check on the estimation of  $\gamma$  using (8), the unadjusted SSD from the 2DVD has been forced to match the SVI in each size bin and the resulting mean  $\gamma_{SVI}$  is computed as:

$$\gamma_{SVI} = \frac{1}{N} \sum_{i=1}^N \frac{N_{SVI}(D_i)}{N_m(D_i)} \dots\dots\dots(12)$$

where  $N$  is the number of size bins,  $N_{SVI}(D_i)$  is the SVI-measured concentration for the  $i^{th}$  bin, and the corresponding 2DVD-measured  $N_m(D_i)$  is obtained as in (6). For the case shown in Fig. 3.3 the  $\gamma_{SVI}$  was found to be 2.46 which is in close agreement with  $\gamma = 2.21$ . For the other snow events listed in Table 1 the  $\gamma$  comparisons are given in Table 4. As noted in the introduction the SVI gives a measure of the equal-area circular diameter which is not the same as  $D_{app}$  from the 2DVD. We ignore the different estimates of  $D$  from the two instruments is so far as validation of the single camera-2DVD based  $\gamma$ -factor estimation is concerned. A more elaborate discussion of SVI estimation of different measures of  $D$  and related characterization of uncertainties in estimation of  $Z_e$  and  $SR$  are given in Wood et al. (2013).

The area ratio ( $A_r$ ) discussed in Section 2c plays an important role in inverting Böhm's methodology to derive mass from the fall speed. Schmitt and Heymsfield (2010) comment that, "...area-dimensional and mass-dimensional relationships are rarely developed from the same dataset". Fig. 7 shows the frequency of occurrence plot (in log scale) of  $A_r$  vs.  $D_{app}$  for the same 30 Dec 2010 snow event. Also shown are the bin averaged mean and  $\pm 1\sigma$  standard deviation bars along with the power law fit



319  $A_r = 0.71 D_{app}^{-0.08}$ . The variability in  $A_r$  is quite large but in general agreement with  
 320 Zwadzki et al. (2010) who used data from the HVSD but allowed  $A_r > 1$ . The mean fit in  
 321 Fig. 7 is in good agreement with that given in Zawadzki et al; they obtain  $A_r=0.75D^{-0.17}$   
 322 (but their ' $D$ ' is the maximum dimension from the side-view image). A somewhat  
 323 different power law fit was obtained by Schmitt and Heymsfield (2010), who used cloud  
 324 imaging probe on aircraft penetrations of ice clouds aloft (this is not surprising since our  
 325 results are at the surface in heavier snowfall). Schmitt and Heymsfield obtained an  
 326 exponent of  $-0.25$  for the ARM data set (Heymsfield et al. 2004), but their coefficient  
 327 was lower by a factor of 2.

328 The final result from Böhm's methodology is the ability to derive a mean density- $D_{app}$   
 329 power law and Fig. 8 shows the same for the 30 Dec 2010 event. While there is large  
 330 variability in density for a given  $D_{app}$  (especially evident for small particles  $D_{app} < 1$  mm  
 331 which might be related to difficulty in matching such particles from the two camera  
 332 images resulting in erroneous fall speed determination); nevertheless, there is an  
 333 inverse relation between density and  $D_{app}$  and the power law fit is  $\rho=0.15 D_{app}^{-0.86}$  for  
 334 this event (Table 1 gives the coefficient and exponent for the other events). Plots of  $\rho$   
 335 versus  $D_{app}$  from Table 1 using the coefficient ( $\alpha$ ) and exponent ( $\beta$ ) found herein for the  
 336 four snow days are close to the mean climatological relation found by Brandes et al.  
 337 (2007;  $\alpha=0.178$ ,  $\beta=-0.922$ ) as well as Holroyd (1971;  $\alpha=0.17$ ,  $\beta=-1$ ) and Fabry and  
 338 Szyrmer (1999;  $\alpha=0.15$ ,  $\beta=-1$ ) with the caveat that ' $D$ ' in each of the quoted references  
 339 are not calculated in the same manner (see, also, Table 2 from Brandes et al. 2007).  
 340 The exponent of the mass- $D_{app}$  power law is given by  $3+\beta$ ; from Table 1, the latter  
 341 exponent varies between 2.04 to 2.21 generally within the range obtained by Schmitt

and Heymsfield (2010) based on fractal simulations of large aggregates (range between 2.1–2.2), and close to the experimentally obtained exponent of 2.2 for the ARM dataset (Heymsfield et al. 2004).

The liquid equivalent snow rate ( $SR$ ) for the 30 Dec 2010 is calculated as given in (11) using the mean  $\rho-D_{app}$  power law fit from Table 1 for the two snow events that occurred on that day. The  $SR$  is adjusted by the  $\gamma$  factor. Fig. 9 shows the liquid equivalent snow accumulation from the 2DVD compared with the collocated OTT-PLUVIO2 gauge at the Järvenpää site. The maximum  $SR$  during the two snow periods occur at around 1230 and 2200 UTC. The agreement between 2DVD and gauge is very good for this event (accumulations are based on 1-min  $SR$  from 2DVD). From Table 1, the accumulations between the 2DVD and gauge for the other days are also in good agreement. It is difficult to estimate the accuracy of the 2DVD-derived snow rate but assuming the  $\rho-D_{app}$  is ‘exact’ and valid for the entire event, the dominant systematic error would be in the  $\gamma$ -adjustment parameter of the SSD. Otherwise, systematic error would primarily arise due to incorrect estimate of  $\alpha$  and secondarily  $\beta$ .

### *3.2 Reflectivity and $Z_e$ - $SR$ power law*

The reflectivity ( $Z_e$ ) at C-band (frequency 5.5 GHz) is computed from 2DVD-measured 1-min averaged  $N(D_{app})$  and the mean  $\rho-D_{app}$  power law fit (for the entire event), based on the assumptions listed towards the end of Section 2.3. It is well established that for Rayleigh scattering and using the Maxwell-Garnet mixing formula (ice inclusions inside an air matrix) that  $Z_e$  can be expressed as:

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$$Z_e = \left( \frac{1}{\rho_{ice}} \right)^2 \frac{|K_{ice}|^2}{|K_w|^2} \int_{D_{min}}^{D_{max}} \rho_{snow}^2 D^6 N(D) dD \dots\dots\dots(12)$$

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where  $|K_{ice,w}|^2$  are the dielectric factors of solid ice and water. Since the mass of the particle is  $m=\rho V L_{app}$ , it follows that  $Z_e$  can be simply computed (suppressing constants) as the sum( $m^2$ ) over all the particles. Thus, the reflectivity is very sensitive to the  $m$ - $D_{app}$  relation (or, equivalently the  $\rho$ - $D_{app}$ ) as shown by a number of previous studies (e.g., Ryzhkov et al. 1998; Matrosov 2009). Errors can arise from uncertainty in the  $\gamma$ -factor which scales the  $N(D)$  or uncertainty in the coefficient  $\alpha$  and less so in the exponent  $\beta$ . Note that the T-matrix scattering code is used to compute  $Z_e$  at C-band frequency.

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Fig. 10 shows time series comparison of  $Z_e$  from 2DVD, POSS [at Järvenpää site for (a) 30 Dec 2010 event and (b) 6 Jan. 2011] and the scanning Kumpula C-band radar reflectivity data extracted over the same site (areal average over  $1^\circ \times 1$  km). The 2DVD and POSS reflectivities are 1-min averaged whereas the Kumpula radar data were available every 5 min. The 2DVD data are somewhat more ‘noisy’ as compared to POSS due mainly to sampling error (the POSS has a very large sample volume by several orders of magnitude relative to the 2DVD). The sampling error in the 2DVD measure of  $Z_e$  was evaluated by Huang et al. (2011) by using two 2DVD units located side-by-side at a site in Huntsville, AL. They estimated the sampling error for reflectivity (in dBZ units) as 1.36 dB (time window for SSD integration was 1-min). They also estimated the normalized sampling error for  $SR$  as 8.5%. The temporal correlation between the three measures of  $Z_e$  is visually quite good.

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By re-sampling the 2DVD and POSS reflectivities to the Kumpula radar samples, the scatter plot of 30 December 2010 case shown in Fig. 11 is obtained. The bias between POSS and 2DVD  $Z_e$  is 0.11 dB, the standard deviation is 2.9 dB, and the correlation coefficient is 0.92. The corresponding values between Kumpula radar and 2DVD are, respectively, 0.18 dB (slight radar overestimate), 4.68 dB and 0.8. The latter standard deviation values would be even lower if the 2DVD sampling error of 1.3 dB were accounted for.

The 2DVD processing described thus far gives the time series of  $Z_e$  and  $SR$  every minute (i.e., 1-min time integration) for each of the long duration (> 4 h) events listed in Table 1. In order to realize a ‘stable’  $Z_e$ - $SR$  relation the sequential intensity filtering technique (SIFT) described by Lee and Zawadzki (2005) is used along with weighted total least-squares to estimate the coefficient and exponent of the  $Z_e$ - $SR$  power law. The basic time window ( $W$ ) selected is 1 h; the SSDs are ordered by increasing  $Z_e$  in this window; and a moving average of  $M=5$  consecutively ordered SSDs is done to filter the DSDs. The same procedure is performed for the next hour of the event and so on until the entire snow duration is covered. From the filtered DSDs, the  $Z_e$  is re-computed using the appropriate  $\rho$ - $D_{app}$  power law. To re-compute  $SR$ , eq. (11) can no longer be used, rather it is computed as:

$$SR = \frac{\pi}{6} \int \rho(D_{app}) D_{app}^3 V_f N(D_{app}) dD_{app} \dots\dots\dots(13)$$

where  $\rho = \alpha D_{app}^\beta$  is the mean fit, and  $V_f = c - d \cdot \exp(-\kappa D_{app})$  is the mean fit to the measured fall speeds (see example in Fig. 5).

Fig. 12 shows the scatter plot of  $Z_e$  versus  $SR$  and the power law fit for (a) the entire 30 Dec 2010 case (i.e., inclusive of both events listed in Table 3) and (b) 6 Jan. 2011 case. Table 3 shows the  $Z_e$ - $SR$  power law fits for the other three snow days. For reference the FMI climatological relation is  $Z_e=100 SR^2$  (Saltikoff et al., 2010) It is fairly evident that for a given  $Z_e$ , the  $SR$  from the FMI relation will exceed that predicted from Table 3 power law fits. For completeness Table 4 shows the  $\gamma$ -adjustment values, and the parameters  $[c d \kappa]$  of the  $V_f D_{app}$  fit.

### 3.3 Radar-derived snow accumulations

There were three C-band polarimetric radars operating during LPVEx, being located at (see Fig. 4) Kumpula (KUM), Kerava (KER) and Vantaa (VAN). The technical specifications can be found in (Hirsikko et al, 2013; Saltikoff and Nevvonen, 2011). When radar reflectivity is used along with a  $Z_e$ - $SR$  relation to generate, e.g., daily (liquid equivalent) snow accumulation maps, clutter and beam-blockage at low elevation angles can cause loss of signal (in the case of clutter, due to clutter filtering) which manifests as artifacts in the snow accumulation maps. To avoid this problem,  $Z_e$  data from the three radars have been composited, using maximum reflectivity factor from any of the three radars, to generate the snow accumulation map for 30 Dec 2010 as shown in Fig. 13. The peak accumulation is around 12 mm within the city of Helsinki. The solid black dots are the locations of six FMI snow gauges (Vaisalla VRG101 with Tretyakov wind shield; Lanza et al. 2006) and the OTT-PLUVIO at Järvenpää site. The numbers adjacent to the gauge locations are the measured accumulations in mm. The radar composite, of course, depicts quite clearly the spatial variability without any artifacts due to clutter or beam blockages; moreover the radar-based accumulations are in good

agreement with the gauges. Fig. 14 shows the accumulation map using the climatological FMI  $Z_e$ - $SR$  relation and it is readily apparent that, while the spatial variability is generally preserved, the magnitudes of the accumulations are overestimated relative to the gauges. In particular, the peak accumulations are now around 16 mm within the city.

To further detail the radar and gauge comparisons, hourly accumulations are compared in Fig. 15 from one gauge location (solid dot in Fig. 13 with 7.8 mm; this is the Porvoo Harabacka location). Whilst it is clear that the FMI climatological relation overestimates the hourly accumulations soon after the snow begins, the radar-based hourly accumulation agrees well with the gauge (and not just the event totals).

Fig. 16 (panel **a**) shows the scatter plot of daily gauge accumulations versus radar-based accumulations (extracted from the radar composites over the six gauge locations and the gauge at the Järvenpää site) for the 4 days using the  $Z_e$ - $SR$  power laws from Table 3 while panel **b** shows the same except for using the fixed FMI climatological  $Z_e$ - $SR$  relation. The significant feature is the dramatic reduction in bias resulting from using the  $Z_e$ - $SR$  obtained from 2DVD data as listed in Table 3 as compared with the fixed FMI relation. The normalized bias and normalized standard error values are, respectively, 28% and 30.8% when Table 3 is used versus 96.6% and 66.1% for the fixed FMI relation. Note that positive bias implies radar overestimates the gauge values. The slope of a straight line trend passing through the origin is 1.2 for panel **a** versus 1.85 for

panel **b**. It is reasonable to infer that the FMI gauges could have underestimated the snow amounts due to wind and type of shielding (i.e., collection efficiency < 1). Recall that the FMI gauges are Vaisala VRG101 with Tretyakov wind shields whose collection efficiency is not known as a function of wind speed. The collection efficiency (or, undercatch) is a complicated function of not only gauge/shield type and wind speed, but also the type of snow particle (dry vs. wet or unrimed vs. rimed) and particle size distribution (Thériault et al. 2012). Thus, there is considerable scatter of the collection efficiency for a given wind speed along with a systematic decrease with increasing wind speed. The latter can be estimated from Rasmussen et al. (2012; their Fig. 11) as mean collection efficiency dropping to 0.75 at wind speed of 4 ms<sup>-1</sup>. If this is taken into account the bias between radar and FMI gauges seen in Fig. 16a would be further reduced.

### *3.4 Spatial reflectivity structure for 30 Dec 2010 and 06 January 2011 cases*

So far, the reflectivity structure nor the environmental/synoptic conditions have been described for the different snow days, as the main emphasis was on the 2DVD data, its processing and product evaluation. However, it is useful to consider the reflectivity structure for the 30 Dec 2010 case (which had the most daily accumulation) and the 06 Jan 2011 case which had the least (Table 2 or Fig. 16), accompanied by very different coefficients/exponents of the  $Z_e$ -SR power laws (respectively, 210/1.63 versus 130/1.44).

472 On 30 Dec 2010 large scale snowfall areas from ESE (the first snowfall from 0800-1300  
473 UTC; see Fig. 10a) and from WNW (second snowfall from 1500-2400 UTC) merged  
474 above southern Finland. These snowfall areas were associated with two low pressure  
475 systems, one centered in Eastern Europe and the main one forming NW of  
476 Scandinavia. At around 1900 UTC the two precipitation systems have merged.  
477 ADMIRARI (Battaglia et al., 2010) LWP (liquid water path) observations reached a  
478 maximum of  $400 \text{ g m}^{-2}$  at 1500 UTC. During the observations ADMIRARI was located in  
479 the backyard of Vaisala which is around 10 km north from Kumpula radar, as shown in  
480 Fig. 4. This is the time when the warm moist area from NW had arrived to the Helsinki  
481 region. During the snowfall the LWP values were ranging between  $100\text{-}150 \text{ g m}^{-2}$ . It  
482 should be noted that these are the slant LWP observations with elevation angle of  $30^\circ$ .  
483 At the time of peak snowfall for the first event (1100-1200 UTC; see Fig. 10a) SVI  
484 images were viewed and it was observed that the main precipitation types were pristine  
485 dendritic type crystals with large aggregates composed of dendrites ( $\sim 8 \text{ mm}$ ) with little  
486 evidence of riming (Newman, personal communication). Fig. 17 shows sample SVI  
487 images at 1120 UTC near the time of maximum  $Z_e$  (see Fig. 10a).

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489 On 06 Jan 2011 south westerly upper level flow from Scandinavia brought warm and  
490 moist air that resulted in a light to moderate snowfall lasting from 0100 to 0800 UTC.  
491 During this period (0500-0700 UTC) the ADMIRARI showed a large amount of  
492 supercooled water with LWP values exceeding  $500 \text{ g m}^{-2}$ . Examination of SVI images  
493 between 0600-0630 showed definite indications of rimed dendrites and columnar  
494 crystals followed by rimed to heavily rimed particles (perhaps graupel). Further in time,



large aggregates (~5-7 mm) appear to be rimed. Also, many smaller rimed snowflakes/crystals (Newman, personal communication). Fig. 18 shows examples of SVI images of rimed aggregates at 0620 UTC.

Fig. 19 shows the rather dramatically different reflectivity structures (at low elevation angle  $0.5^\circ$ ) between the 30 Dec 2010 event (at 1000 UTC) and the 06 January 2011 event (at 0610 UTC). The spatial variability is much more pronounced in the 06 January case (more cellular) as compared to the more conventional spatial variability occurring on 30 Dec. The cellular feature implies weak imbedded convection is likely with more prevalent particle riming as alluded to earlier. This is supported by analysis by Lim et al. (2013) who were able to associate higher spatial variability with enhanced riming of particles. The vertical structures are also different as depicted in the RHI scans in Fig. 20 taken along the radial to the Järvenpää site. Again, the 30 Dec event is much more uniform in the vertical as compared with the 06 Jan event, the latter showing more evidence of cellular structure in the vertical implying imbedded convection and enhanced riming.

Finally, in Fig. 21, the snow accumulation map for 06 Jan event is shown using the 2DVD-derived  $Z_e$ -SR power law, which can be compared with Fig. 13. The snow accumulations for this event (see, also Table 1) are much smaller compared with 30 Dec case additionally showing much more spatial variability. Note these are not daily

totals but restricted to the period 0000-0900 UTC since the 2DVD stopped working at 0824 UTC on this day thereby missing another major snowfall event later on this day.

#### 4. Summary and Conclusions

The estimation of the mean density-size and  $Z_e$ - $SR$  power laws using 2D-video disdrometer measured fall speed, apparent diameter and snow size distribution (SSD) along with Böhm's (1989) methodology is described in some detail. A method for adjusting the concentration based on single camera data to account for loss of particles that do not satisfy the matching criteria (when 2 cameras are used) is shown to be reasonable when compared with Snow Video Imager (SVI)-based concentrations. Snow events which occurred on four days of the Light Precipitation Validation Experiment (LPVEx) were chosen based on light wind speeds ( $< 4 \text{ ms}^{-1}$ ) at the measurement site with liquid equivalent snow accumulations ranging from 1.5 mm to 4 mm. While there is large variability of fall speed, area ratio and derived density which is attributed to natural variability of snow type, shape and porosity, the mean density- $D_{app}$  (or, mass- $D_{app}$ ) and  $Z_e$ - $SR$  power laws do vary from event-to-event. The reflectivity derived from the 2DVD data is shown to be in good agreement with colocated POSS and with scanning C-band radar, while the liquid equivalent snow accumulation is shown to be in good agreement with colocated OTT-PLUVIO gauge at the measurement site. The radar-based snow accumulations using the 2DVD-derived  $Z_e$ - $SR$  relations for the four days are in good agreement with a network of six FMI snow gauges (and the OTT-PLUVIO gauge) and outperform the accumulations derived from a climatological  $Z_e$ - $SR$  relation used by the Finnish Meteorological Institute (FMI). The normalized bias between radar-derived and gauge accumulation is reduced from 96%

(overestimate by the FMI climatological relation) to 28% when using the  $Z_e$ -SR based on 2DVD data. The normalized standard error is also reduced significantly from 66% to 31%. While the FMI gauges were equipped with Tretyakov wind shields, undercatchment due to wind cannot be ignored and could account for underestimation of snow accumulations by 20-30% for wind speeds in the range 3-4 ms<sup>-1</sup>; this would reduce the bias between radar and gauge accumulations even further.

For two of the days with widely different coefficients of the  $Z_e$ -SR power law, the reflectivity structure showed significant differences in spatial variability (both horizontal and vertical). Liquid water path estimates from radiometric data also showed significant differences between the two cases. Examination of SVI particle images at the measurement site corroborated these differences in terms of unrimed versus rimed snow particles.

In summary, the findings reported herein support the application of Böhm's (1989) methodology for deriving the mean density-size and  $Z_e$ -SR power laws using data from 2D-video disdrometer. Evaluation of radar-based snow accumulation against a network of snow gauges independently supports the latter conclusion notwithstanding the limited number of events available for analysis.

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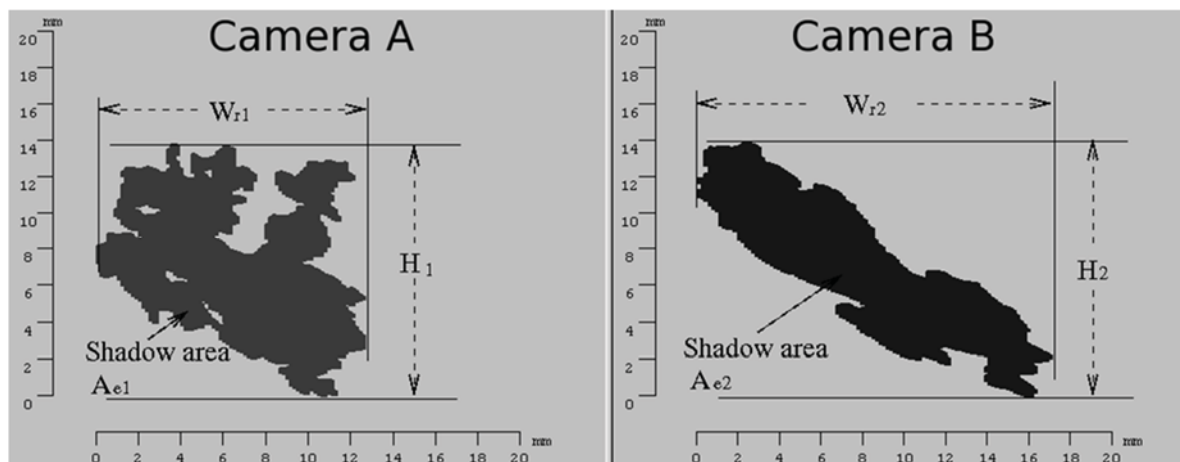
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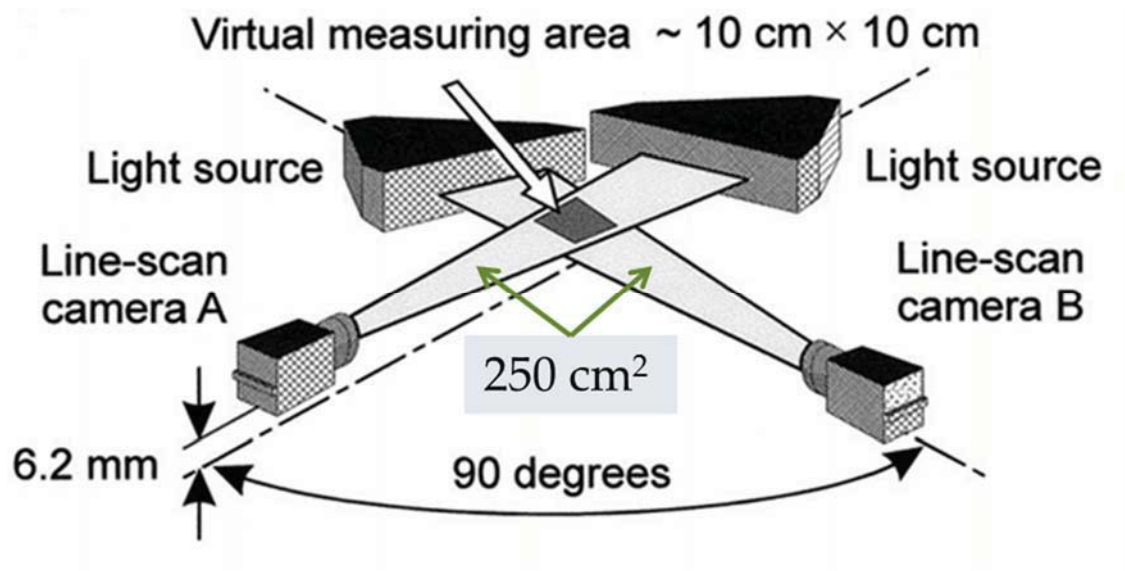
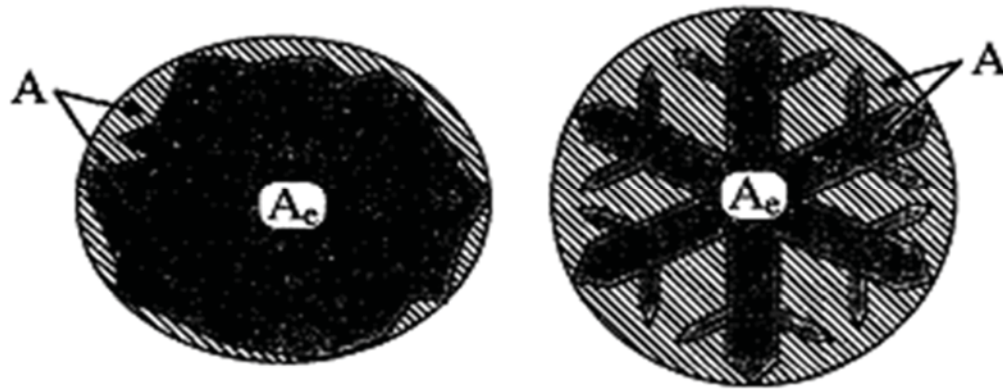
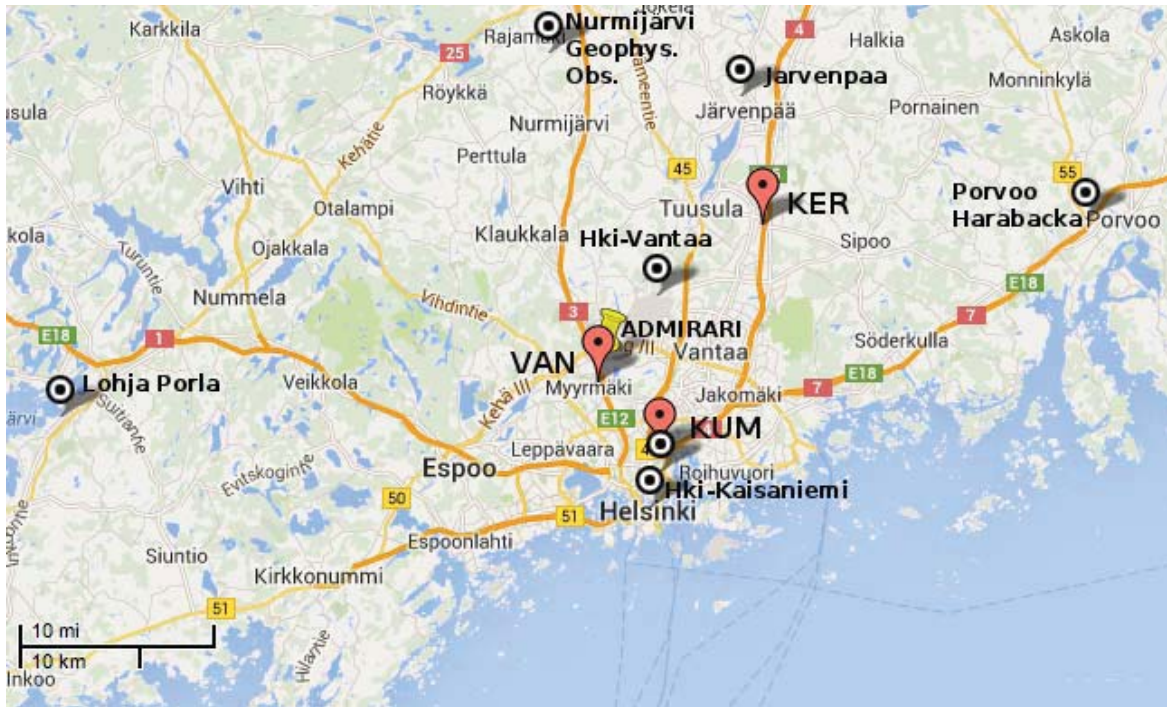


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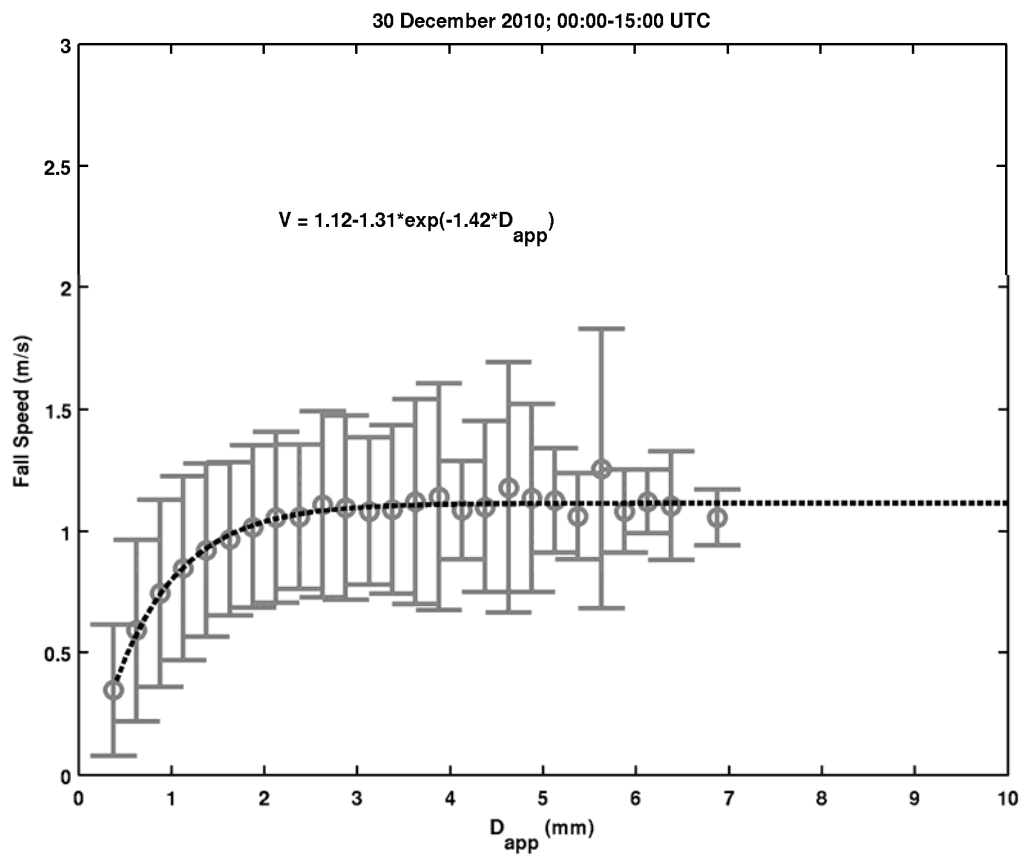


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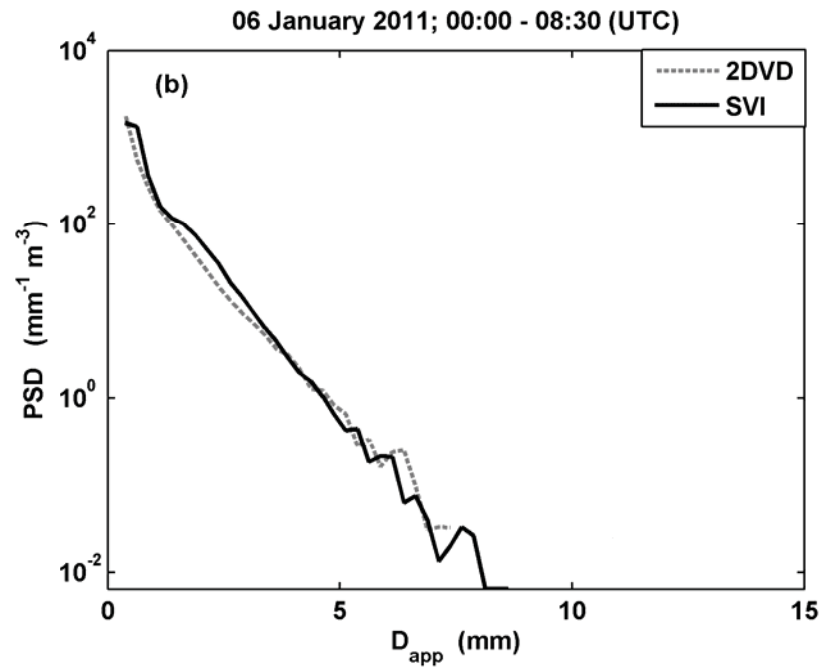
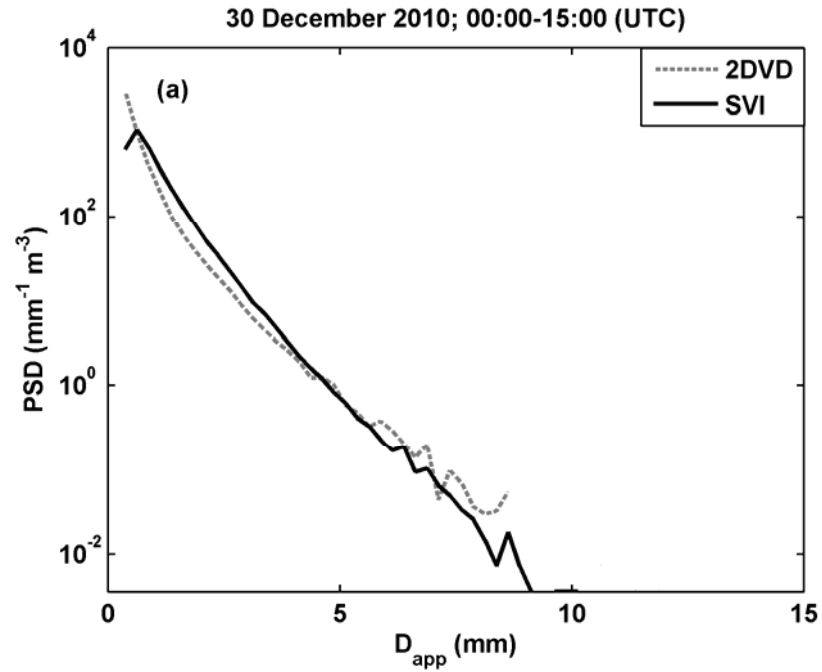


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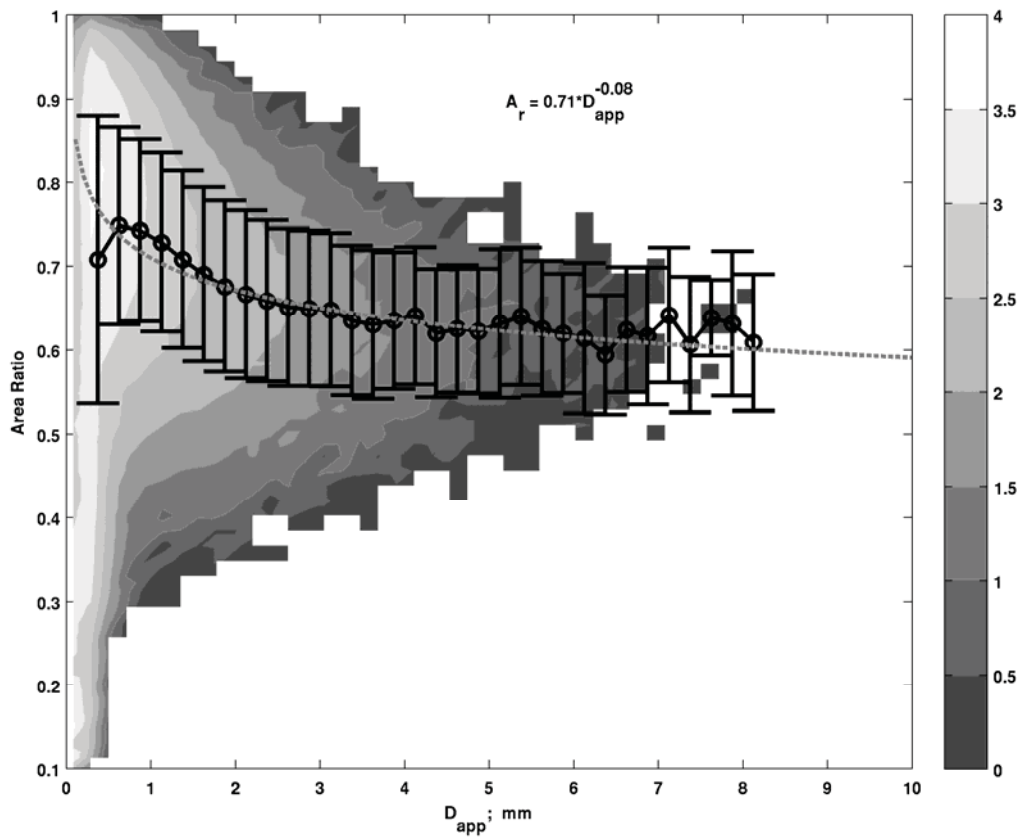


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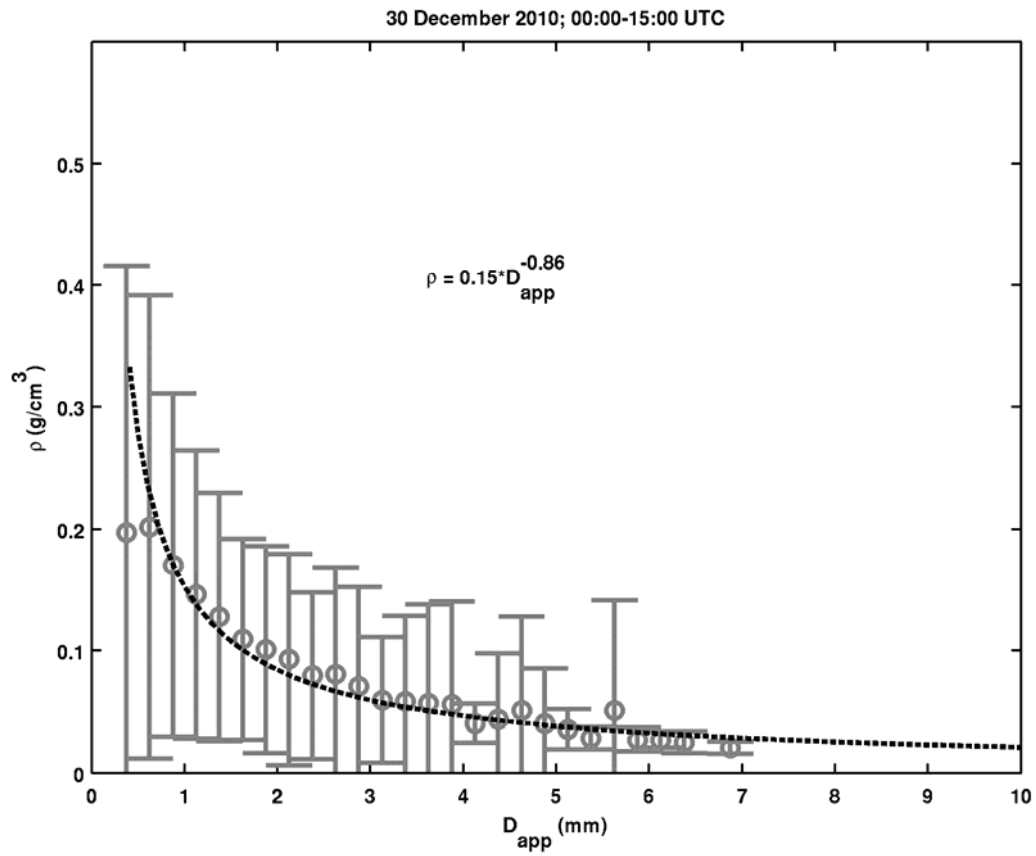
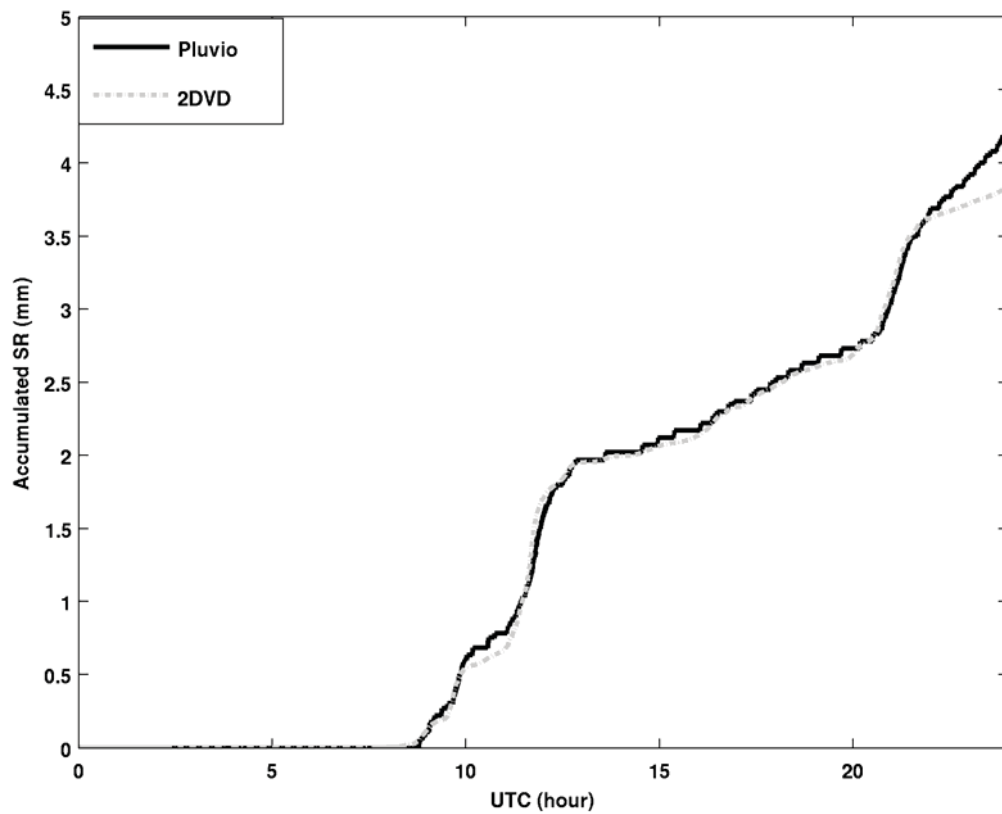


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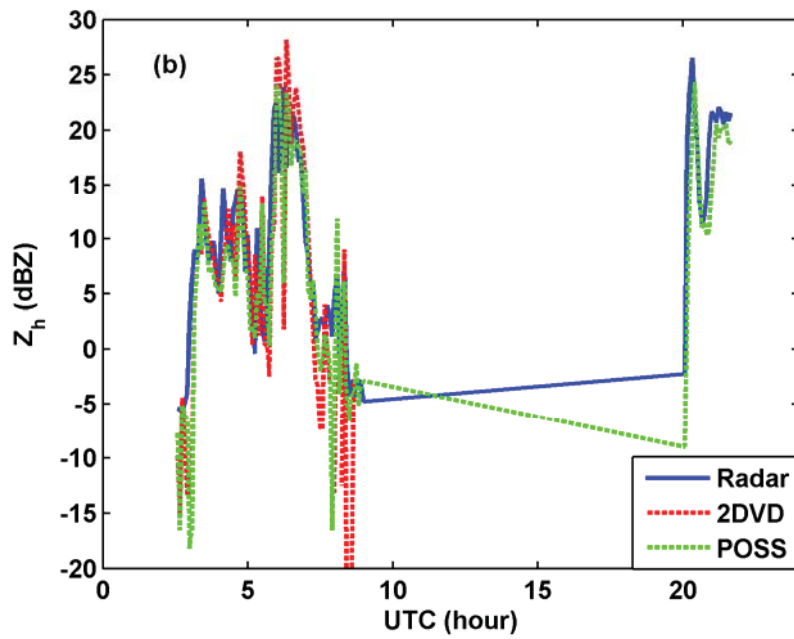
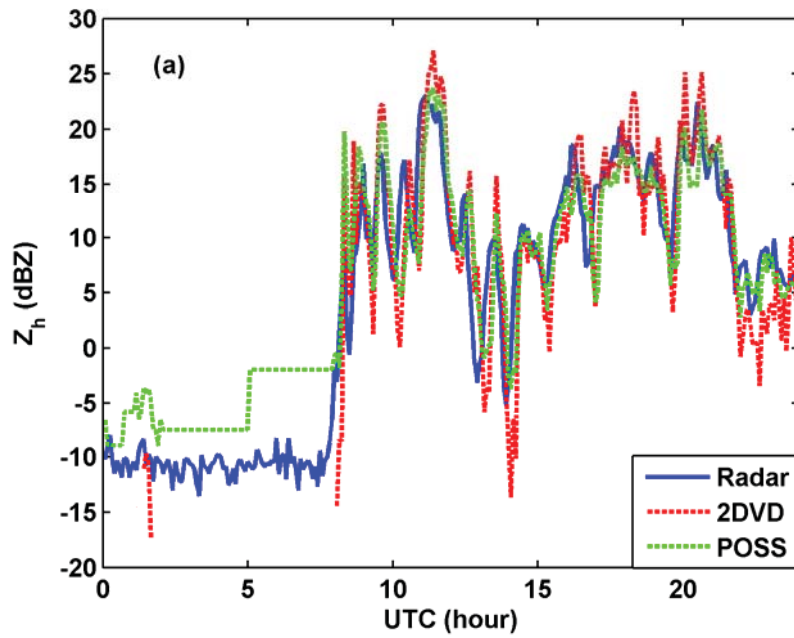


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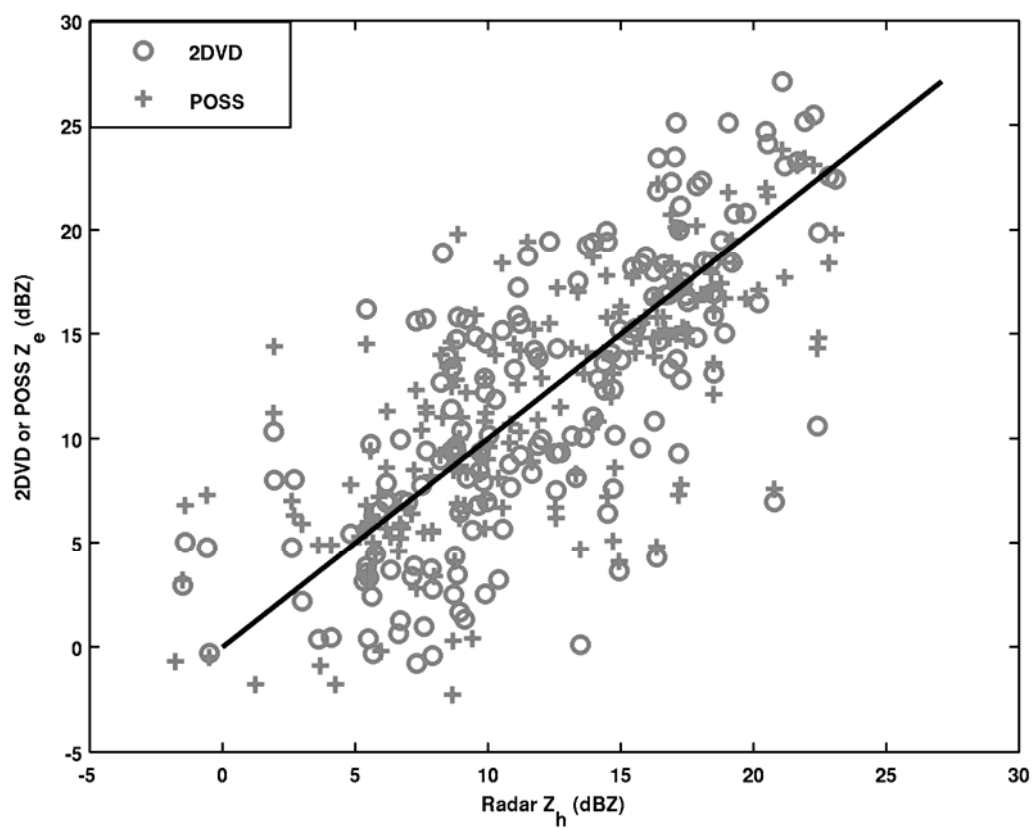


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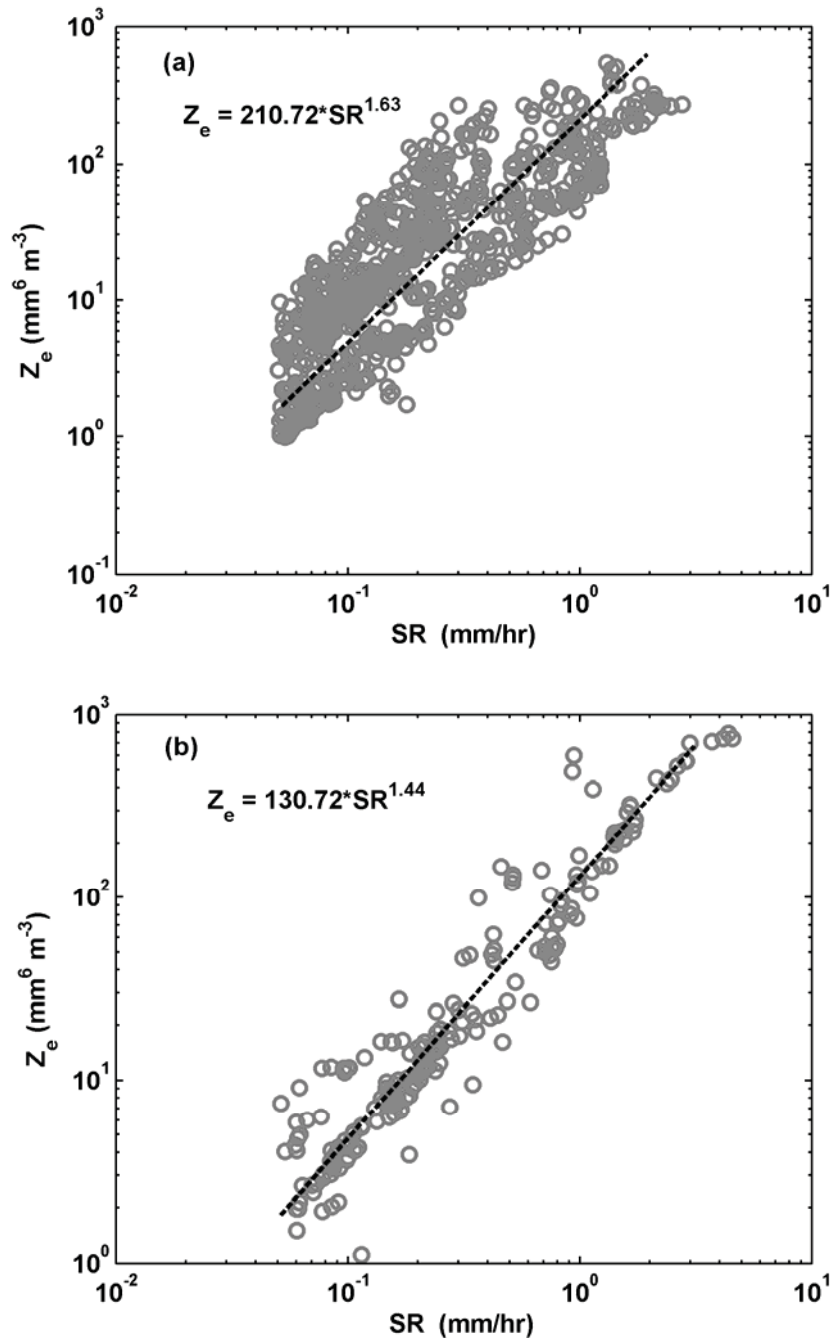


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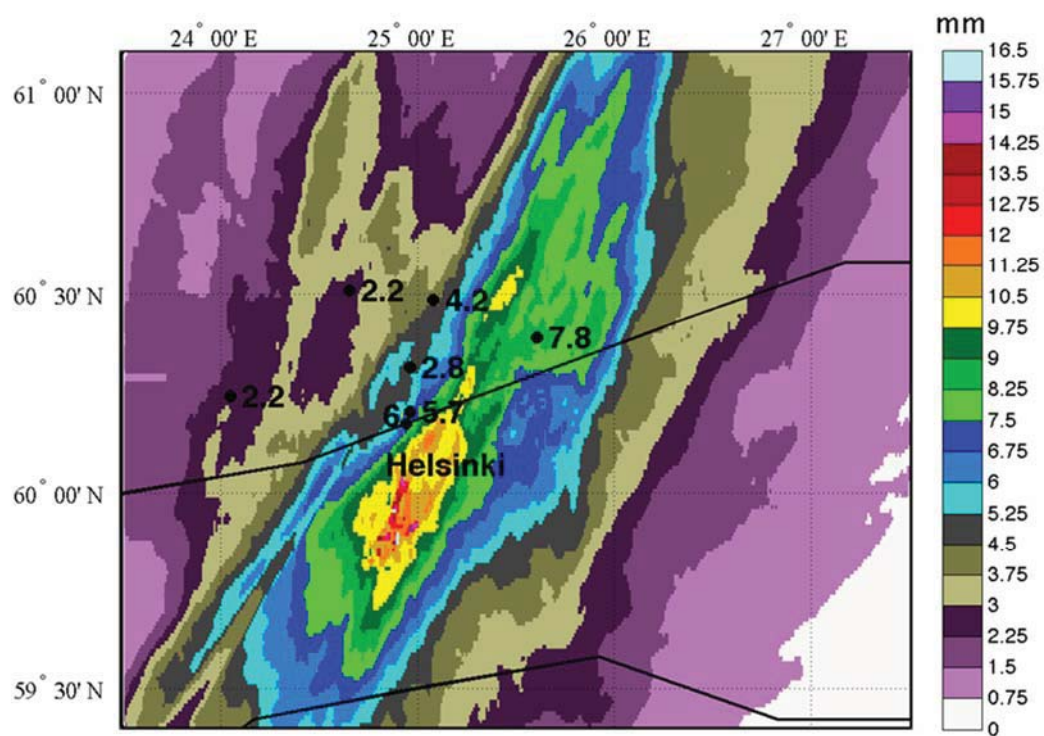


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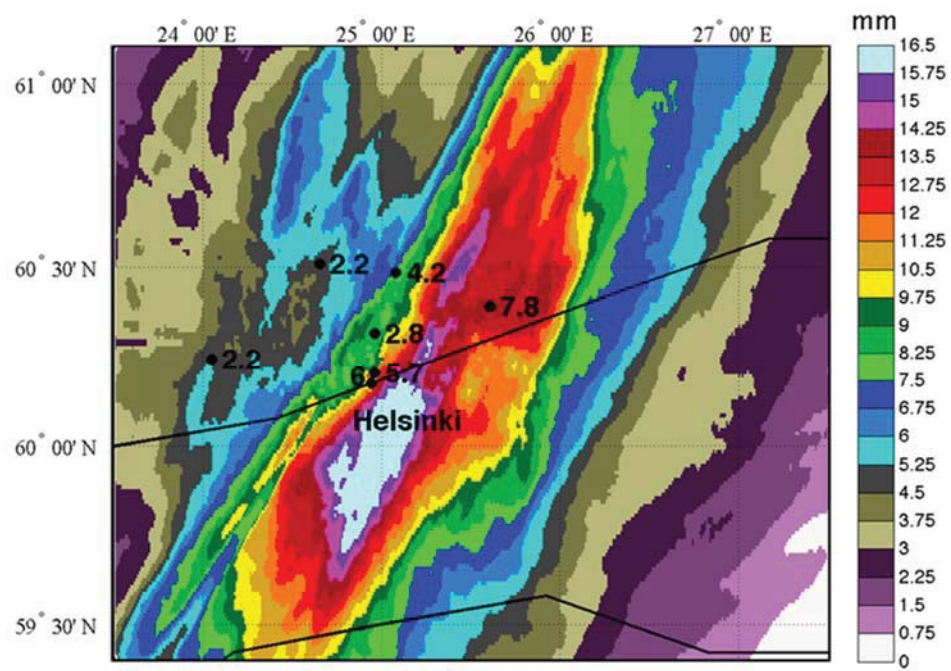
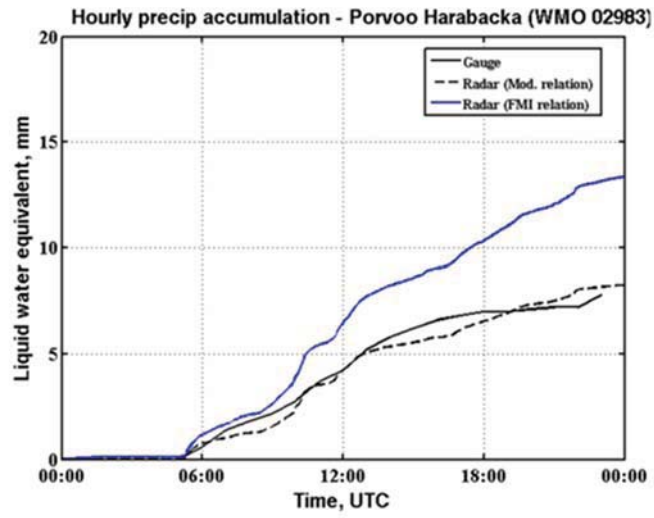


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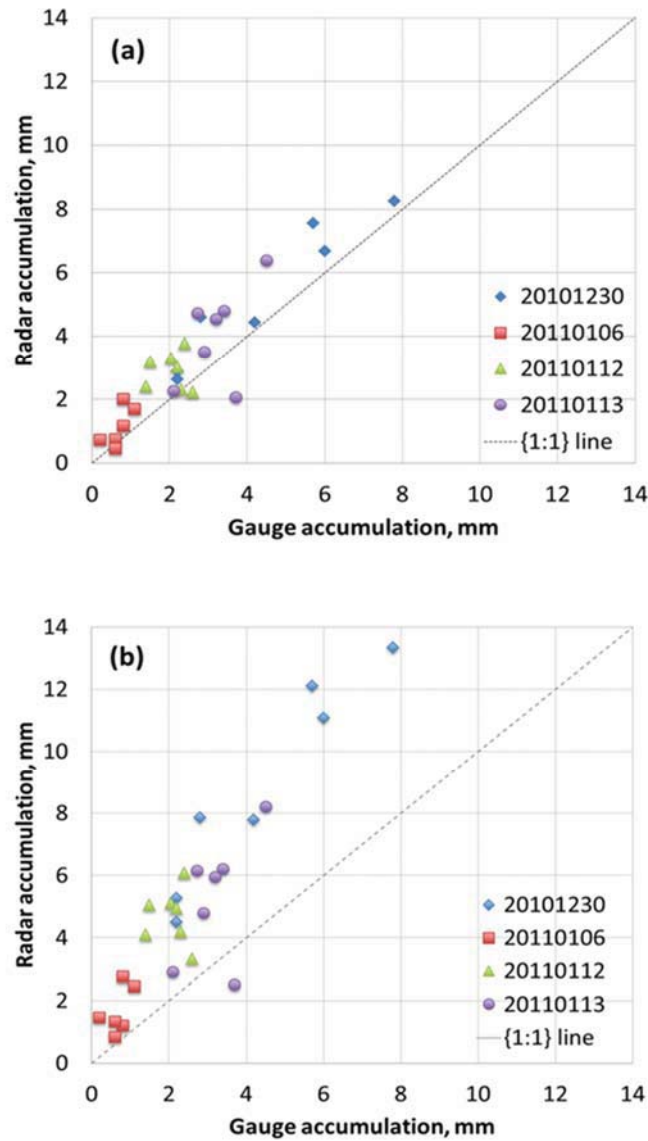
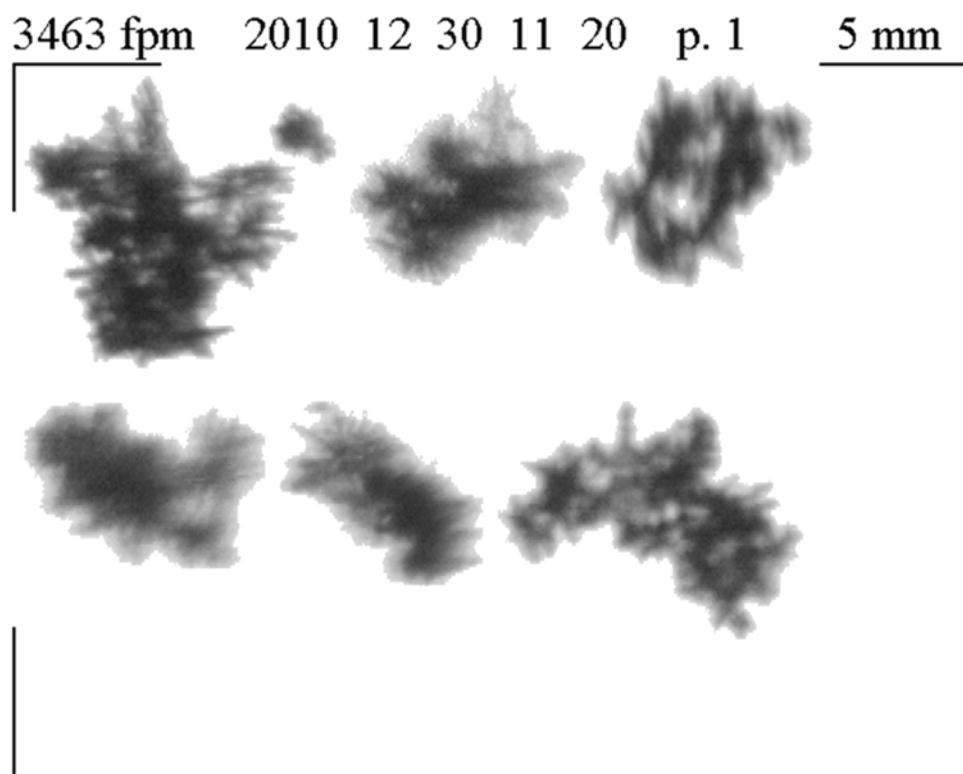
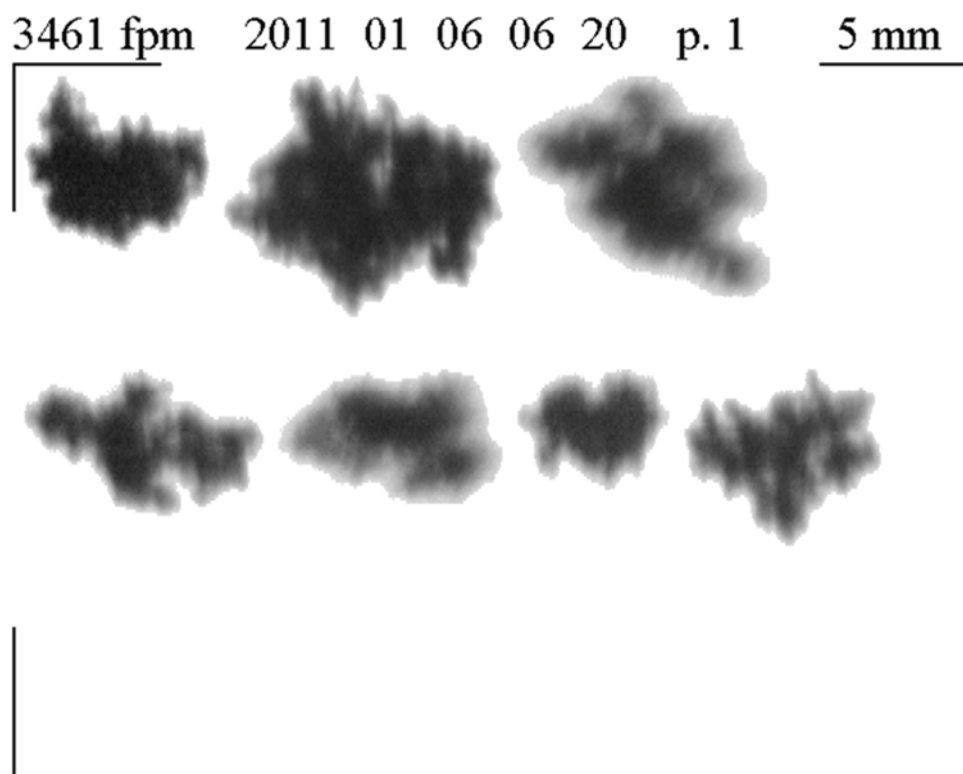


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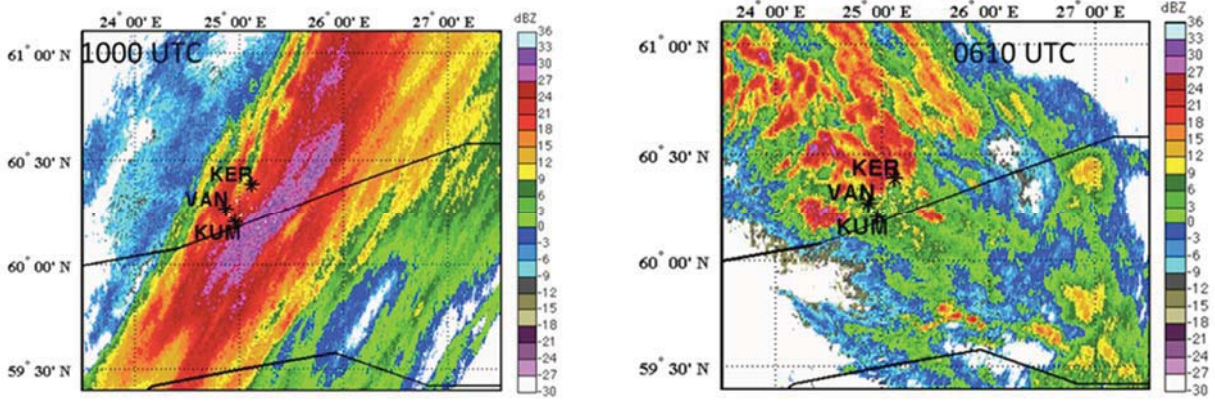




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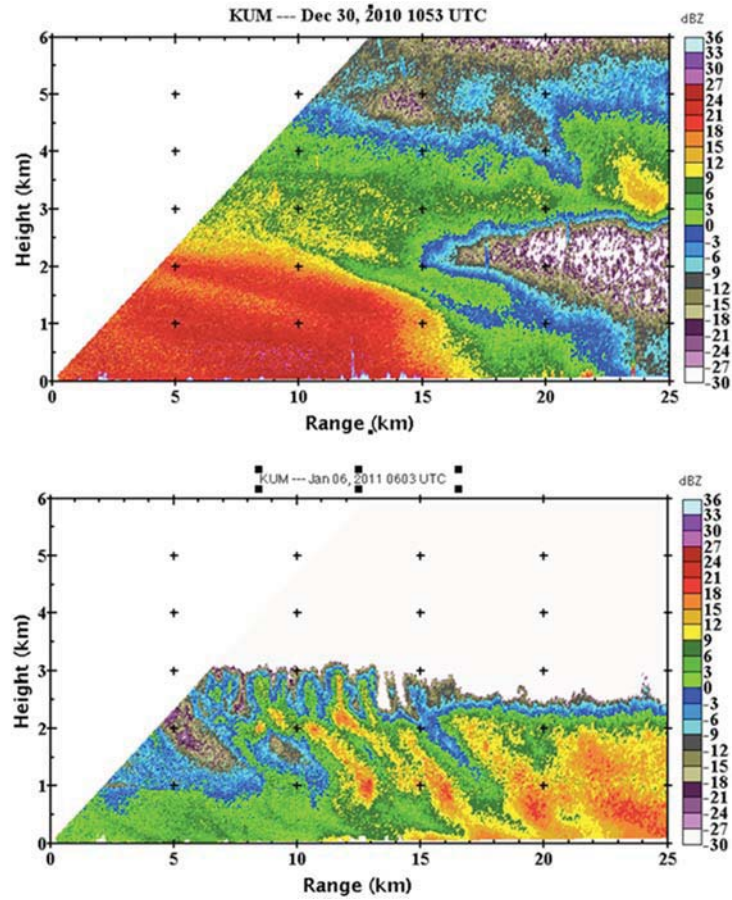


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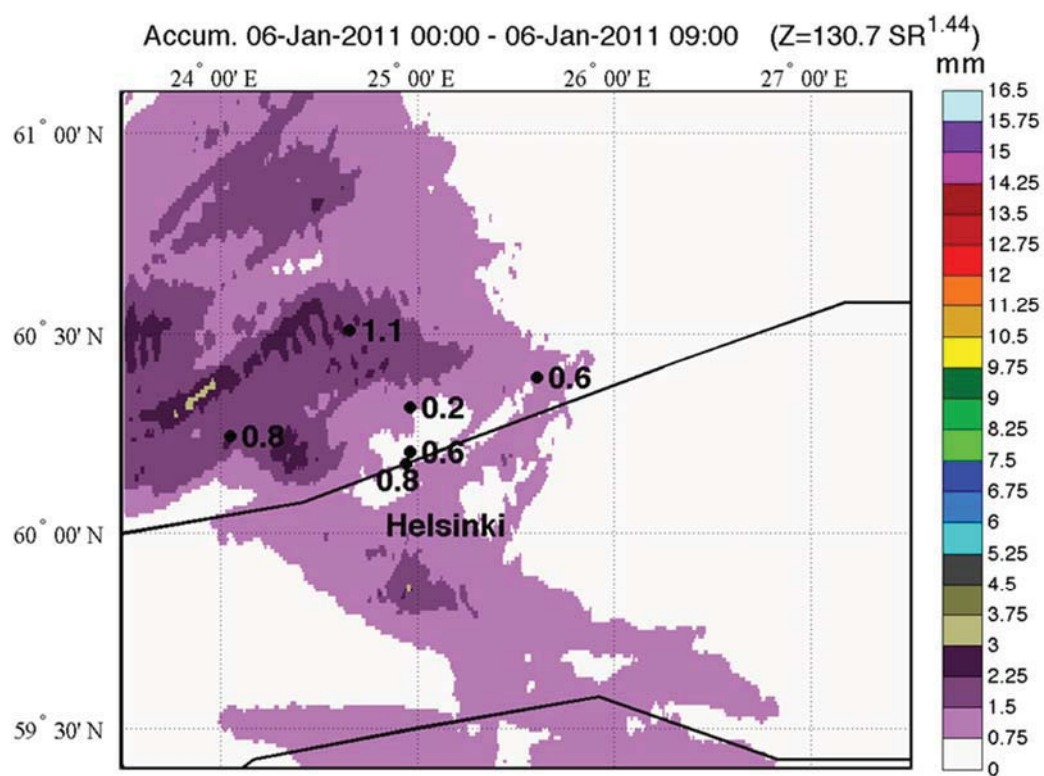


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Event	Time (UTC)	Temperature C	2DVD accum (mm)	OTT-PLUVIO2 accum (mm)
30 Dec 2010	a.0800-1300 b.1500-2359	a. -9 b. -8	3.84	4.24
06 Jan 2011	0230-0830	-7	1.53	1.53
12 Jan 2011	a.0800-1230 b.2230-2359	a. -3 b. -3	3.36	2.05
13 Jan 2011	0000-0500	-4	2.77	2.73

853

Table 2: Coefficient  $\alpha$  and exponent ( $\beta$ ) of  $\rho$ - $D_{app}$  power law fit (density in g cm<sup>-3</sup> and  $D_{app}$  in mm)

Event	Time (UTC)	$\alpha$	$\beta$
30 Dec 2010	a.0800-1300	a. 0.15	-0.86
	b.1500-2359	b. 0.15	-0.96
06 Jan 2011	0230-0830 <sup>†</sup>	0.17	-0.79
12 Jan 2011	a.0800-1230	a. 0.23	-0.88
	b.2230-2359	b. 0.19	-0.8
13 Jan 2011	0000-0500	0.19	-0.8

<sup>†</sup> the 2DVD stopped working at 0824 on this day



Table 3: The  $Z_e = a \cdot SR^b$  power law for the four days. Note  $Z_e$  in  $\text{mm}^6 \text{m}^{-3}$  and  $SR$  in  $\text{mm h}^{-1}$ .

	<b>a</b>	<b>b</b>
30 Dec. 2010	210.72	1.63
06 Jan. 2011	130.72	1.44
12 Jan. 2011	209.20	1.67
13 Jan. 2011	134.86	1.81

855 † The power laws are derived for application to all events occurring during the  
856 day.  
857

Table 4: The  $\gamma$ -adjustment factor and the  $V_f$ - $D_{app}$  fit parameters [c d  $\kappa$ ].

Event	Time (UTC)	$\gamma$	$\gamma_{SVI}$	$c$	$d$	$\kappa$
30 Dec 2010	a.0800-1300	a. 2.21	a. 2.46	1.20	1.54	1.16
	b.1500-2359	b. 1.94	b. 2.57			
06 Jan 2011	0230-0830	2.55	2.92	1.37	1.37	1.25
12 Jan 2011	a.0800-1230	a. 3.53	a. 3.6	1.37	1.85	1.78
	b.2230-2359	b. 2.23	b. 2.18			
13 Jan 2011	0000-0500	2.23	4.24	1.34	1.34	0.95

† The  $V_f$ - $D_{app}$  fits are derived for application to all events occurring during the day (note:  $D_{app}$  in mm and  $V_f$  in  $\text{m s}^{-1}$  ).